

4 - Beyond variational inference

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Winter School on Mathematical Statistics, Luxembourg, Dec'20

Outline

- 1 – Models with latent variables in ecology (statistical ecology)
- 2 – Variational inference for incomplete data models (statistics)
- 3 – Variational inference for species abundances and network models (statistical ecology)
- 4 – Beyond variational inference (statistics)

Part 4

Algorithmic improvements

Guaranties about variational estimates

Combining variational inference with ...

- Frequentist inference

- Bayesian inference

Conclusion (?)

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Algorithmic improvements

Borrowed from many fields.

- ▶ Optimization: generic stochastic gradient descent (#21) or more dedicated approaches [HBWP13]
- ▶ Bayesian inference: Variational tempering [MMA⁺16]
- ▶ Machine learning: Variational autoencoders [KW14,KW19]
 - use neural networks to learn the variational parameters with more flexibility

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Statistical guarantees: *no big picture*

Accuracy of variational estimates.

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Balanced results.

- ▶ Mean-field approximation provides consistent estimates (binary SBM affiliation: [ZZ20])
- ▶ Naive implementation may yield instabilities [GJM19,ZZ20]

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Positive results.

- ▶ Some results for specific models [HOW11]
- ▶ Some attempts for a general theory via M -estimation [WM19]
- ▶ Most studied case: mean-field VEM binary stochastic block-model (see next)

Binary stochastic block-model

A series of results: [CDP12,BCCZ13,MM15,ZZ20]

- ▶ Consistency of variational estimates
- ▶ Asymptotic normality of variational estimates
- ▶ Class recovery (node classification, including LBM)

Binary stochastic block-model

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Why does it work? Theorem 3.1 in [CDP12] states that

$$P \left(\sum_{z \neq z^*} \frac{p_{\theta}(Z = z | Y)}{p_{\theta}(Z = z^* | Y)} > t \right) = O(ne^{-\kappa nt})$$

uniformly in z^* , with $\kappa = \kappa(\theta)$.

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- ▶ Intuition: $p_\theta(Z | Y)$ is asymptotically Dirac, which belongs to $\mathcal{Q} = \mathcal{Q}_{fact}$.
- ▶ The 'largest gap' algorithm [CDR12] takes advantage of a similar concentration #23
- ▶ The proofs do not easily adapt to other VEM

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Frequentist inference

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Maximum likelihood inference.

$$\hat{\theta}_{MLE} = \arg \max_{\theta} \log p_{\theta}(Y)$$

is intractable because the likelihood involves an integration over the latent Z

$$\text{PLN:} \quad \log p_{\theta}(Y) = \sum_i \log \left(\int_{\mathbb{R}^p} p_{\Sigma}(Z_i) \prod_j p_{\beta}(Y_{ij} | Z_{ij}) dZ_i \right)$$

$$\text{SBM:} \quad \log p_{\theta}(Y) = \log \left(\sum_{Z \in [\mathcal{K}]^n} \prod_i p_{\pi}(Z_i) \prod_{i,j} p_{\alpha,\beta}(Y_{ij} | Z_i, Z_j) \right)$$

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The (log-)likelihood is far from being the only admissible estimation function

→ think, e.g., of M -estimation

Composite likelihood

Sum of partial likelihoods:

$$\text{PLN: } \hat{\theta}_{CL} = \arg \max_{\theta} \sum_i \sum_{j,k} \log p_{\theta}(Y_{ij}, Y_{ik}) \quad \text{only requires } \int_{\mathbb{R}^2}$$

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Practical implementation.

- ▶ EM algorithms can be designed to maximize composite likelihoods
- ▶ Getting $\hat{\theta}_{CL}$ is still demanding (many terms in the sum: np^2 for PLN, n^3 for SBM)
- ▶ $\hat{\theta}_{VEM}$ usually provides a (very) good starting point

Bayesian inference

Bayesian inference

Reminder.

- ▶ Prior: $p(\theta)$
- ▶ Latent: $p(Z | \theta)$
- ▶ Observed: $p(Y | Z, \theta)$
- ▶ Posterior:

$$\theta_{PLN} = (\beta, \Sigma), \quad \theta_{SBM} = (\pi, \alpha, \beta)$$

$$p(\theta, Z | Y) = \frac{p(\theta) p(Z | \theta) p(Y | \theta, Z)}{p(Y)}$$

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$$w^b = \frac{p(\theta^b, Z^b | Y)}{q(\theta^b, Z^b)}$$

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- ▶ Sequential Monte-Carlo: construct a sequence of distribution going from $q(\theta, Z)$ to $p(\theta, Z | Y)$

Sequential Monte-Carlo sampling

Principle. [DDJ06] $U = (\theta, Z)$

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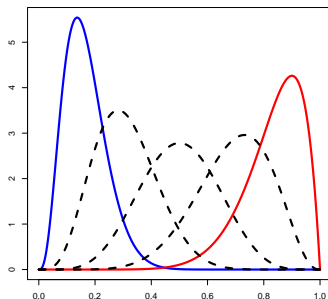
- ▶ given $p_{start}(U)$
- ▶ aiming at $p_{target}(U) = p(U | Y)$
- ▶ sample from a sequence of distributions

$$p_{start} = p_0, p_1, \dots, p_{H-1}, p_H = p_{target}$$

with

$$p_h(U) \propto p_{start}(U)^{1-\rho_h} p_{target}(U)^{\rho_h}$$

and $0 = \rho_0 < \rho_1 < \dots < \rho_H = 1$



see #24 for tuning of the ρ_h

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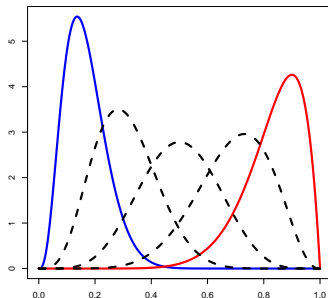
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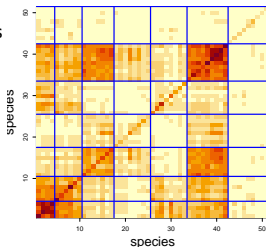
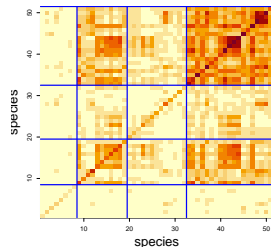
see #24 for tuning of the ρ_h

Most often: $p_{start} = p_{prior}$ (long way to the posterior)

VBEM: directly use $p_{start} = p_{VBEM}$

VEM: use (approximate) Louis formulas [Lou82] to derive $p_{start} = p_{VEM}$ [DR19]

Back to the tree interaction network

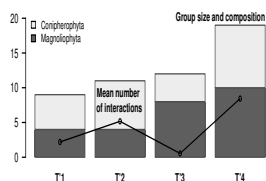
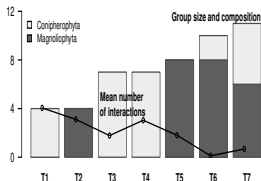
No covariate: $\widehat{K}_{ICL} = 7$ Taxonomic dist.: $\widehat{K}_{ICL} = 4$ 

Y_{ij} = number of shared parasites
 x_{ij} = taxonomic distance
 $Y_{ij} \sim \mathcal{P}(\exp(x_{ij}^T \beta + \alpha_{Z_i Z_j}))$

Estimates:

$$\widehat{K}_{ICL} = 4 \quad \widehat{\beta} = -.317$$

- Taxonomy (partially) explains the links (smaller \widehat{K})
- Distant species share less parasites ($\widehat{\beta} < 0$)
- The remaining structure is not related to taxonomy



Tree network: model selection

Model selection.

- ▶ Number of groups K
- ▶ Set S of relevant covariates: $S \subset \{\text{taxonomy, geography, phylogeny}\}$

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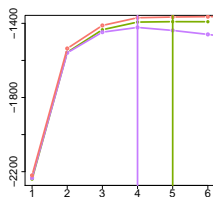
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Choosing K for a given S :

$$p(K | Y, S) \propto p(Y | S, K)$$

here : $S = (\text{taxonomy, geography})$

Averaging over K : #26



$\log p(Y | S, K)$

$J_{\hat{\theta}, \hat{q}}$

VICL

Tree network: model selection

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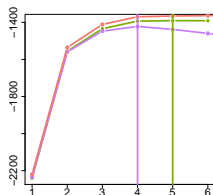
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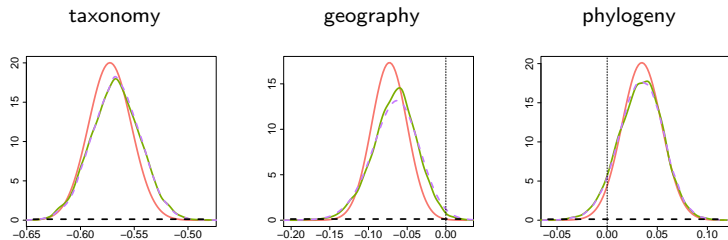
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vICL

Variable selection. $p(S | Y) = \sum_K p(S, K | Y)$

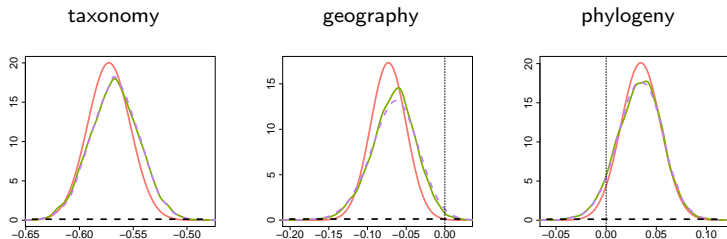
$$P\{x = (\text{taxo.}, \text{geo.}) | Y\} \simeq 70\%, \quad P\{x = (\text{taxo.}) | Y\} \simeq 30\%$$

Tree network: significance

Parameter posterior distribution for $S = (\text{taxonomy, geography, phylogeny})$:

Legend: $q_{VEM}(\beta_j)$, $p(\beta_j | S, \hat{K}(S), Y)$, $p(\beta_j | S, Y)$

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Why so many steps to go from $q_{VEM}(\beta_j)$ to $p(\beta_j | Y)$?

Correlation between estimates.

	(β_1, β_2)	(β_1, β_3)	(β_2, β_3)
$p_{VEM}(\beta)$	-0.012	0.021	0.318
$p(\beta Y)$	-0.274	-0.079	-0.088

+ $p(Z | Y)$ in #27

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Latent variable models (in ecology).

- ▶ Very useful (hope you're convinced)

Variational inference (computational side).

- ▶ Computationally efficient
- ▶ Reasonably easy to implement (hope you're convinced too)

Variational inference (theoretical side).

- ▶ Generic analysis of variational estimation still to do
- ▶ Alternatively: combine with other inference methods to combine computational efficiency with pre-existing statistical guarantees

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Reparametrization trick

Denoting by ψ the variational parameter, The VE step aims at minimizing

$$KL[q_\psi(Z) \parallel p_\theta(Z | Y)] = \mathbb{E}_{q_\psi} \log \frac{q_\psi(Z)}{p_\theta(Z | Y)}$$

Stochastic gradient descent requires an unbiased estimate of the gradient $\nabla_\psi \mathbb{E}_{q_\psi}(\cdot)$... which is *not* provided by sampling $Z^b \stackrel{\text{iid}}{\sim} q_\psi$ to estimate \mathbb{E}_{q_ψ} .

Trick [KW14, KW19]. Suppose there exist a fix distribution q^0 and a function f , such that¹

$$\epsilon \sim q^0 \quad \Rightarrow \quad Z = f(\epsilon, \psi) \sim q_\psi,$$

Then, sampling $\epsilon^b \stackrel{\text{iid}}{\sim} q^0$ provides an unbiased estimate of the gradient:

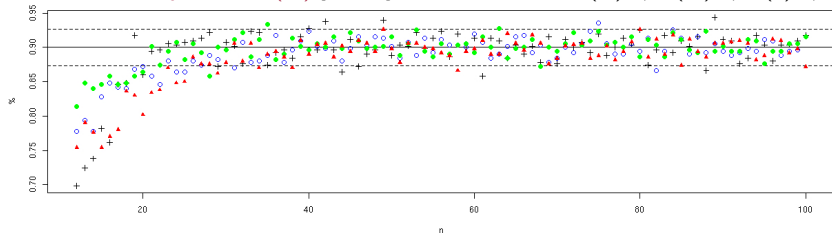
$$\nabla_\psi \mathbb{E}_{q_\psi} \log \frac{q_\psi(Z)}{p_\theta(Z | Y)} \simeq \nabla_\psi \left(\frac{1}{B} \sum_b \log \frac{q_\psi(f(\epsilon^b, \psi))}{p_\theta(f(\epsilon^b, \psi) | Y)} \right)$$

Back to #5

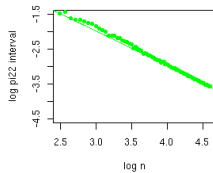
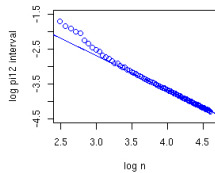
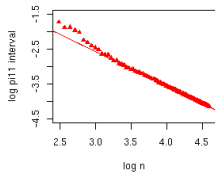
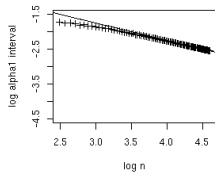
¹Think of $q^0 = \mathcal{N}(0, I)$, $\psi = (\mu, \Sigma)$, $q_\psi = \mathcal{N}(\mu, \Sigma)$.

VBEM for binary SBM

Posterior credibility intervals (CI) [GDR12]: Actual level for π_1 (+), γ_{11} (\triangle), γ_{12} (\circ), γ_{22} (\bullet)



Width of the posterior CI. π_1 , γ_{11} , γ_{12} , γ_{22}



→ Width $\approx 1/\sqrt{n}$ for π_1 and $\approx 1/n = 1/\sqrt{n^2}$ for γ_{11} , γ_{12} and γ_{22} .

Back to #7

Largest gap algorithm

► **Degree** of a node: $D_i = \sum_{j \neq i} Y_{ij}$

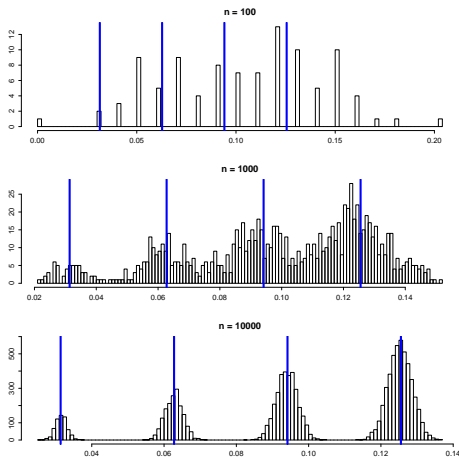
► Mean connection from group k :

$$\bar{\gamma}_k = \sum_{\ell} \pi_{\ell} \gamma_{k\ell}$$

► Degree distribution²

$$(D_i \mid Z_i = k) \sim \mathcal{B}(n-1, \bar{\gamma}_k)$$

► **Concentration** of $D_i/(n-1)$ around $\bar{\gamma}_{Z_i}$ at exponential rate



→ Ensures consistency [CDR12] (including sparse regime)

Back to #8

²Balanced affiliation model = nasty case: $\pi_k \equiv 1/K, \gamma_{kk} = \gamma_{in}, \gamma_{k\ell} = \gamma_{out} \Rightarrow \bar{\gamma}_k \equiv (\gamma_{in} + (K-1)\gamma_{out})/K$

Sequential importance sampling scheme

Consider $U = (\theta, Z)$

Distribution path: set $0 = \rho_0 < \rho_1 < \dots < \rho_{H-1} < \rho_H = 1$,

$$p_h(U) \propto p_{\text{start}}(U)^{1-\rho_h} \times p_{\text{target}}(U)^{\rho_h}$$

$$\propto p_{\text{start}}(U) \times r(U)^{\rho_h},$$

$$r(U) = \frac{p(U)p(Y | U)}{p_{\text{start}}(U)}$$

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Sequential sampling. At each step h , provides

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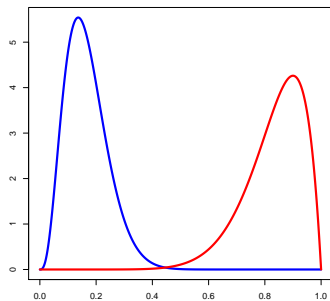
$$\mathcal{E}_h = \{(U_h^m, w_h^m)\}_m = \text{weighted sample of } p_h$$

Tune ρ_{h+1} to keep the efficient sample size sufficiently high at each step.

→ Doable because $r(U)$ does not depend on ρ .

Sequential sampling: in pictures

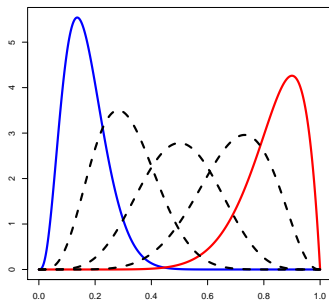
► p_{start} = proposal, p_{target} = target



Back to #13

Sequential sampling: in pictures

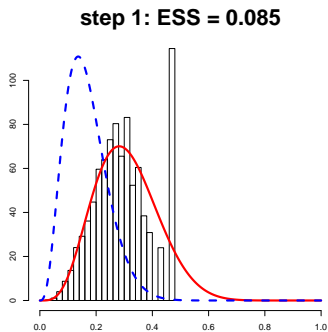
- ▶ p_{start} = proposal, p_{target} = target
- ▶ Intermediate distributions $p_{\text{start}} = p_0, p_1, \dots, p_H = p_{\text{target}}$



Back to #13

Sequential sampling: in pictures

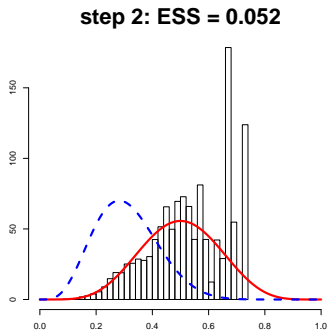
- ▶ p_{start} = proposal, p_{target} = target
- ▶ Intermediate distributions $p_{\text{start}} = p_0, p_1, \dots, p_H = p_{\text{target}}$
- ▶ Iteratively:
use p_h to get a sample from p_{h+1}



Back to #13

Sequential sampling: in pictures

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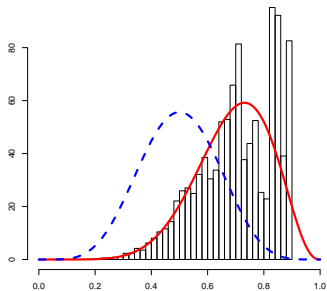


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Sequential sampling: in pictures

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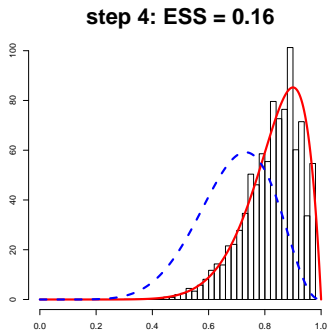
step 3: ESS = 0.078



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Sequential sampling: in pictures

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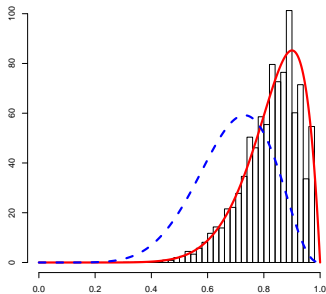


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Sequential sampling: in pictures

- ▶ p_{start} = proposal, p_{target} = target
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- ▶ Iteratively:
use p_h to get a sample from p_{h+1}

step 4: ESS = 0.16



+ resampling/propagation to avoid complete degeneracy [DR19]

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Residual 'graphon'

Graphon representation of (π, α) . [LR16,DR19]

$$\phi_K : (0, 1) \times (0, 1) \mapsto \mathbb{R} \quad \text{block wise constant}$$

For a given set S , averaging over K gives

$$\widehat{\phi}(u, v) = \mathbb{E}(\phi_K(u, v) \mid Y, S) = \sum_K p(K \mid Y, S) \mathbb{E}(\phi_K(u, v) \mid Y, S, K)$$

Residual 'graphon'

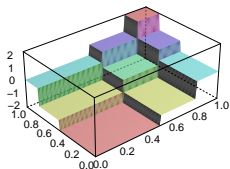
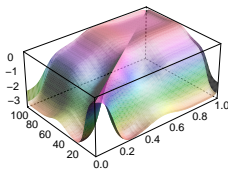
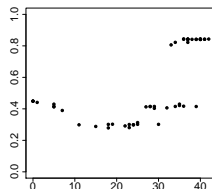
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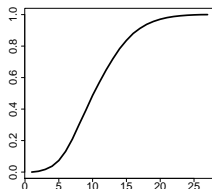
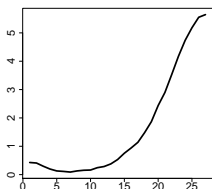
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SBM graphon

 $\hat{\phi}$ for the tree network U_i vs nb. neighbors

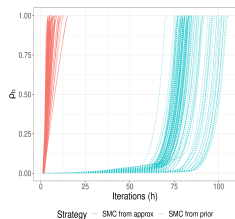
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SMC path

Tree network, $S = \{taxo., geo.\}$  ρ_h 

$$KL \left(\rho_h(Z) \parallel \prod_i \rho_h(Z_i) \right)$$

Simulations



from [DR19]

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